# Description of unpolarized Drell－Yan and SIDIS processes within TMD factorization 

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## Introduction

> I present the joined fit of the DY and SIDIS data and the extraction non-perturbative TMD distributions

## Main messages:

- Joined description of DY and SIDIS is consistent and does not meet any problem
- We do not see any tension between HERMES and COMPASS SIDIS data
- TMD non-perturbative evolution is universal


## TMD factorization formula (in $\zeta$-prescription)



- Each data-point is a product (convolution) of three independent non-perturbative functions
- Functions do not "cross-talk" and could be modeled independently
- Each function is responsible for a separate kinematic variable
- Rapidity AD: $\mathcal{D} \rightarrow Q$ and $b$
- TMD PDF: $F \rightarrow x$ and $b$
- TMD FF: $\quad D \quad \rightarrow \quad z$ and $b$

Hard part and TMD evolution

## NNLO \& $\mathrm{N}^{3} \mathrm{LO}$

## Model for RAD

$$
\mathcal{D}(b, \mu)=-\frac{K(b, \mu)}{2}=\underbrace{\mathcal{D}_{\text {pert }}\left(b^{*}(b), \mu\right)}_{\begin{array}{c}
\text { NNLO \& N } \\
\text { resumbed }{ }^{3} \mathrm{LO}
\end{array}}+c_{0} b \cdot b^{*}(b), \quad b^{*}=b\left(1+b^{2} / B_{N P}^{2}\right)^{-1 / 2}
$$



Model for (optimal) TMD distribution

$$
F(x, b)=\underbrace{C(x, b) \otimes f_{1}(x)}_{\text {NNLO } \& \mathrm{~N}^{3} \mathrm{LO}} f_{N P}(x, b)
$$

Resummation equivalent: NNLL' \& $\mathbf{N}^{3} \mathbf{L L}(?)$

In $\zeta$-prescription: $\mu \sim Q$
Matching scales $\mu_{\text {OPE }}$ are intrinsic for each function


Difference between NNLO and $\mathrm{N}^{3} \mathrm{LO}$ is not that important

Fit strategy and the test of universality


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Fit strategy and the test of universality


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Fit strategy and the test of universality


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Check of universality


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Check of universality


Check of universality


Check of universality


There are plenty of details/questions

- How to cut the data?
- Where is the limit of TMD factorization?
- Power corrections:
$\checkmark$ Induced (ATLAS, LHCb) (linear in $q_{T}$ ?)
- Kinematic
- In the definition of collinear frame
- Target mass and produced mass
- Universality and correlations
- ... many others ...
- What do we learn from it?

Test by inclusion of the data with

$$
q_{T}<\delta \cdot Q
$$

unpolarized DY

[I.Scimemi, $\dot{A} V, 1706.01473$ ]
unpolarized SIDIS


$\begin{array}{llll}8 & 16 & 24 & 32\end{array}$
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## TMD factorization for SIDIS

Proof of factorization is done in the Breit frame

$$
\begin{aligned}
& \text { Breit frame } \\
& q_{T}^{2}=\frac{p_{T}^{2}}{z^{2}} \frac{1+\gamma^{2}}{1-\varsigma^{2}} \\
& x_{1}=-x \frac{2}{\gamma^{2}}\left(1-\sqrt{1+\gamma^{2}\left(1-\frac{\mathbf{q}_{T}^{2}}{Q^{2}}\right)}\right), \quad z_{1}=z \frac{x_{1}}{x} \frac{1+\sqrt{1-\varsigma^{2}}}{2\left(1-\frac{\mathbf{q}_{T}^{2}}{Q^{2}}\right)} \\
& \text { Lab frame } \\
& \gamma=\frac{2 M x}{Q} \\
& \varsigma=\gamma \frac{m}{z Q}
\end{aligned}
$$

In practice: $q_{T}<0.25 Q$

- Most part of data is not TMD factorisable.
- Low $z$ 's are not accessible
- H1, ZEUS data have no TMD points, too low z.

Test of importance of power correction

These are not all power corrections, but only those that we know how to account

| include $(m / Q)$ | yes | no | yes | yes | no | no |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| include $(M / Q)$ | yes | yes | no | yes | no | no |
| include $\left(q_{T} / Q\right)$ in kinematics | yes | yes | yes | no | no | no |
| include $\left(q_{T} / Q\right)$ in $x_{S}, z_{S}$ | yes | yes | yes | yes | yes | no |
| $\chi^{2} / N_{p t}$ | 1.00 | 1.00 | 1.09 | 1.06 | 1.16 | 1.31 |

Most important corrections are $\frac{M}{Q}$ and $\frac{q_{T}}{Q}$ from the rotation Breit $\rightarrow$ Lab

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Data survived after the cut


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## Example of SIDIS data No contradiction between HERMES and COMPASS



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Example of low-energy DY Some problem with normalization Large-x, nuclear corrections,...


$+15 \%$

LHC data within TMD factorization



Evolution : 2 parameters TMDPDF : 5 parameters + PDF TMDFF : 4 parameters + NNFF


Different NP functions are almost decorrelated

$$
\begin{aligned}
f_{N P}(x, b) & =\exp \left(-\frac{\lambda_{1}(1-x)+\lambda_{2} x+x(1-x) \lambda_{5}}{\sqrt{1+\lambda_{3} x^{\lambda_{4}} \boldsymbol{b}^{2}}} \boldsymbol{b}^{2}\right), \\
D_{N P}(x, b) & =\exp \left(-\frac{\eta_{1} z+\eta_{2}(1-z)}{\sqrt{1+\eta_{3}(\boldsymbol{b} / z)^{2}}} \frac{\boldsymbol{b}^{2}}{z^{2}}\right)\left(1+\eta_{4} \frac{\boldsymbol{b}^{2}}{z^{2}}\right),
\end{aligned}
$$

> Evolution : 2 parameters TMDPDF : 5 parameters + PDF TMDFF : 4 parameters + NNFF

Different NP functions are almost decorrelated

Fit quality essentially depends on the collinear input.

Vary NNPDF within the $1 \sigma$ band

$$
\chi^{2} / N_{p t} \in[0.8,6 .]
$$

We cannot estimate accurately the PDF uncertainty.

$$
F(x, b)=C\left(x, b, \mu_{O P E}\right) \otimes \underbrace{f_{1}\left(x, \mu_{O P E}\right)}_{ \pm \delta f(\text { reweighted })} \underbrace{f_{N P}(x, b)}_{ \pm \delta f_{N P}}
$$




$$
F(x, b)=C\left(x, b, \mu_{O P E}\right) \otimes \underbrace{f_{1}\left(x, \mu_{O P E}\right)}_{ \pm \delta f(\text { reweighted })} \underbrace{f_{N P}(x, b)}_{ \pm \delta f_{N P}}
$$




$s$-quark $x=0.5$


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unpolarized TMD-distributions


## Universal TMD evolution kernel



$$
\mathcal{D}_{\mathrm{NP}}(b, \mu)=\mathcal{D}_{\mathrm{perp}}\left(b^{*}, \mu\right)+c_{0} b b^{*}, \quad b^{*}=b / \sqrt{1+b^{2} / B_{N P^{2}}}
$$

- Linear asymptotic at $b \rightarrow \infty$ (ed.assumption)
- RAD is independent on PDF set


## Universal TMD evolution kernel Comparison



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## TMD factorization is consistent and universal approach

- Large bulk of data DY + SIDIS described by same TMD distribution ( $+\pi \mathrm{DY}$ )
- Extracted NP-functions are (almost) uncorrelated
- Previous estimation of limits for TMD factorization confirmed $q_{T} / Q<0.25$
- Perfect perturbative stability
- Target mass corrections and proper definition of the kinematic variables helps
- Strong sensitivity to collinear input (restriction to PDFs?)
- Definite model bias
- Lack external information on distributions (models,lattice,...)

$$
\text { artemide v2.02 } \rightarrow \mathrm{v} 2.03 \text { (soon) }
$$

https://github.com/VladimirovAlexey/artemide-public

- Bug fixing
- Growing functionality: DY, SIDIS, different in/out-states
- New tools to estimate uncertainties.

